

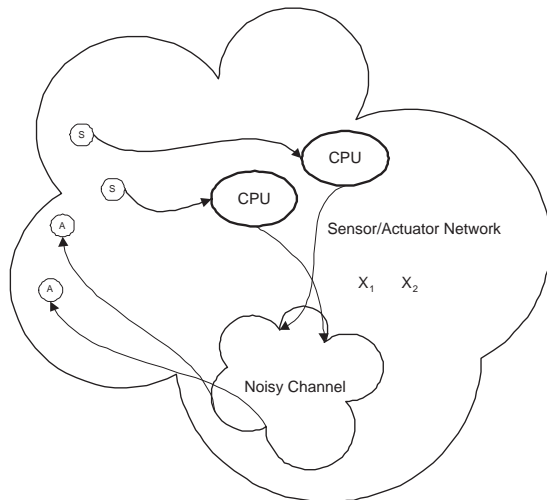
Streaming Source Coding with Delay

Cheng Chang

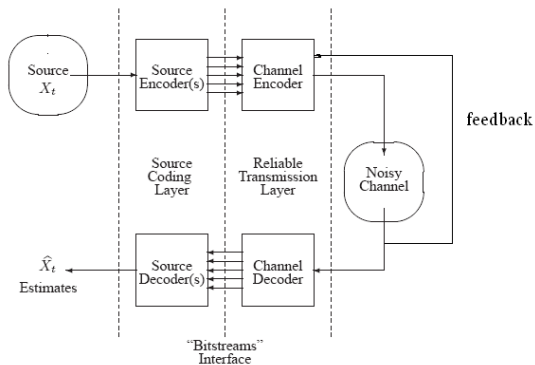
Committee in charge: Anant Sahai, Chair
Kannan Ramchandran
David Aldous

Motivation

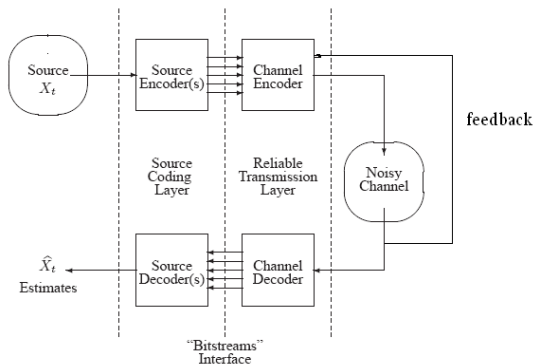
- Applications which care about end-to-end delay
 - ▶ Online gaming, video conferences....
 - ▶ Control and Communication (Sahai 2001), Remote surgery...



Source channel coding and delay

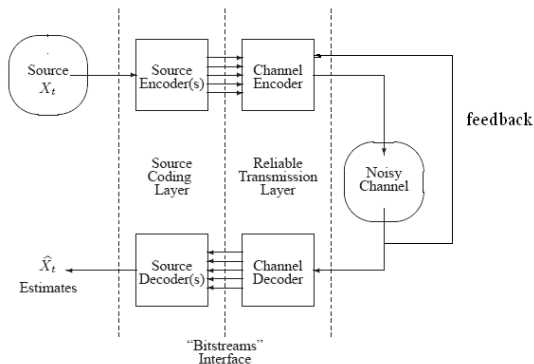


Source channel coding and delay



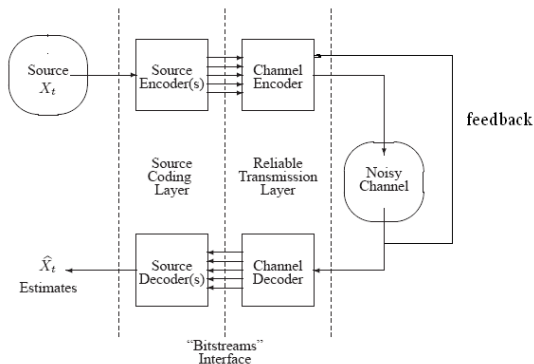
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Source channel coding and delay



- Fixed length block coding (Shannon), X_t is a long block ready at time 0
- Hard real-time (Gilbert/ Neuhoff, Shannon), X_t gradually available

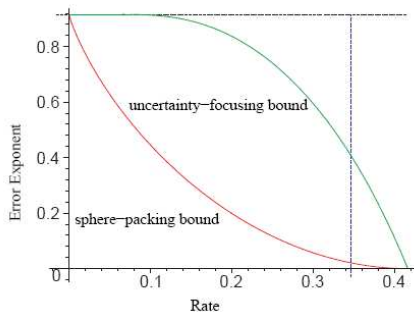
Source channel coding and delay



- Fixed length block coding (Shannon), X_t is a long block ready at time 0
- Hard real-time (Gilbert/ Neuhoff, Shannon), X_t gradually available
- Streaming with long delays (this talk)— X_t gradually available, long delay

Block length and delay are not the same thing (Sahai 2006)

- Streaming feedback error exponent with deterministic delay
 - ▶ Upper bound: Focusing bound (Simsek 2004), not completely understood
 - ▶ True only if both streaming AND with feedback



What about source coding?

- Streaming source coding with delay (this talk)
 - ▶ Complete characterization of the error exponent for point-to-point coding
 - ▶ Lower and upper bounds for distributed source coding
 - ▶ Price of ignorance

What about source coding?

- Streaming source coding with delay (this talk)
 - ▶ Complete characterization of the error exponent for point-to-point coding
 - ▶ Lower and upper bounds for distributed source coding
 - ▶ Price of ignorance
- Why block length and delay are not the same thing?
 - ▶ Dominant error event — most likely trouble maker (minimum effort by source/ channel)
 - ▶ Block coding: block error events (BSC ($\epsilon = 0.1$) flip half of the bits)
 - ▶ Streaming coding, decode X_t at time $t + \Delta$: past vs future (More challenges)



Outline

1 Problem setup and motivation

- Motivation
- Streaming coding with delay

2 Main results

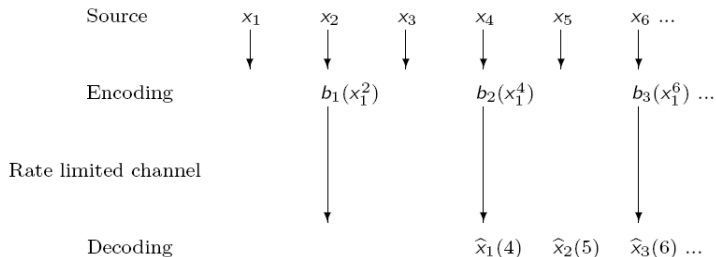
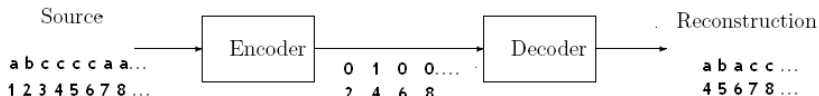
- P2P lossless source coding
- P2P lossy
- Distributed source coding
- Source coding with side-information, an upper bound

3 Conclusions and future works

- Past vs future
- Open problems

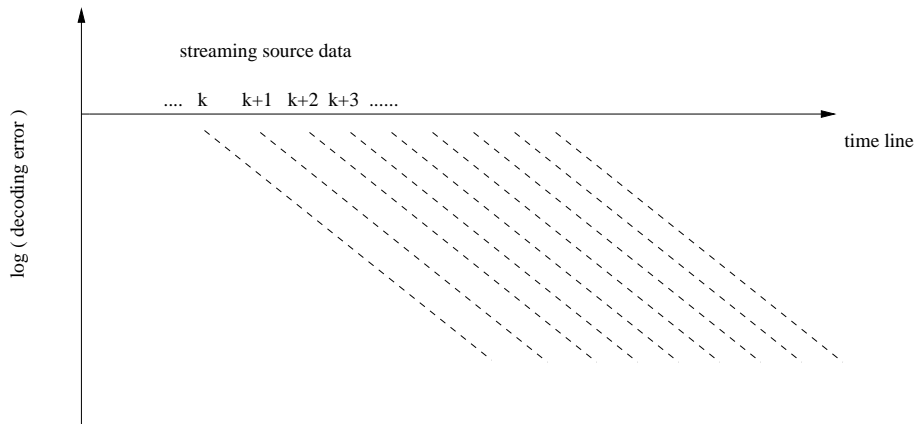
Streaming source coding with delay

- Source $\mathcal{X} = \{a, b, c\}$, $R = \frac{1}{2}$, $\Delta = 3$



Delay constrained error exponent (fixed-delay)

$$\Pr(\widehat{x}_i(i + \Delta) \neq x_i) \sim 2^{-\Delta E(R)} \text{ for large } \Delta$$



Architecture issues: P_e , Δ , R

- Symbol error P_e
- End to end delay Δ
- Communication rate R bits/ second

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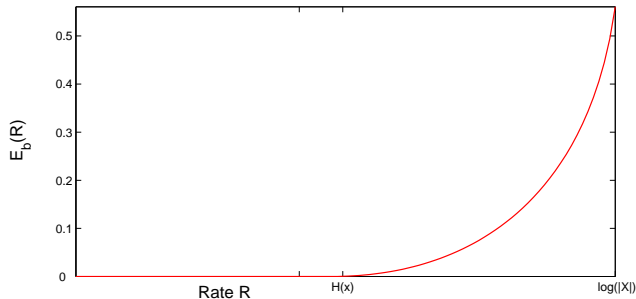
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 - ▶ Given P_e and Δ : $R \sim E^{-1}\left(-\frac{\log P_e}{\Delta}\right)$
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- Asymptotic result, need non-asymptotic results for small Δ
- Non-asymptotic information theory/ redundancy rate/ Minimum description length/ universal lower bounds on error exponents (Kieffer, Baron, Shamir, Gallager, Sahai, C)

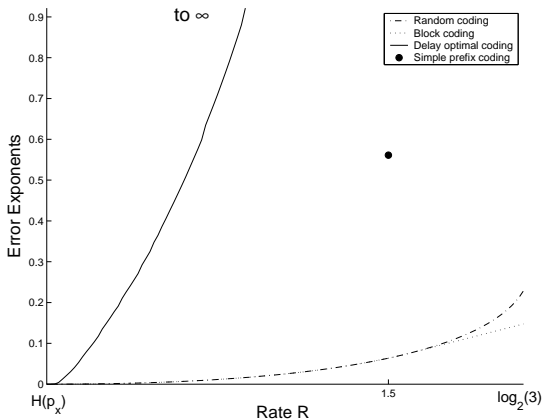
Block coding error exponent (Gallager, Csiszár)

$$E_b(R) = \min_{q: H(q) \geq R} D(q \| p_x) = \sup_{\rho \geq 0} \{ \rho R - (1 + \rho) \log \left[\sum_x p_x(x)^{\frac{1}{1+\rho}} \right] \}$$



The focusing operator

$$E(R) = \inf_{\alpha > 0} \frac{1}{\alpha} E_b((\alpha + 1)R)$$



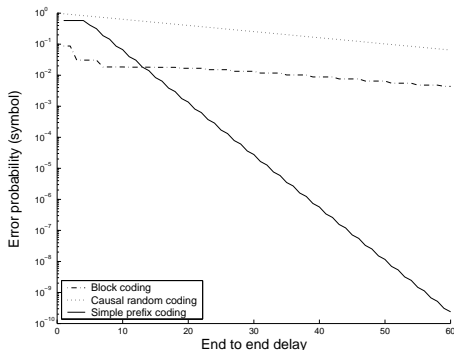
Non-asymptotic result

- A simple variable length code beats block coding (0.65, 0.175, 0.175)

$AA \rightarrow 0$

$AB \rightarrow 1000$ $AC \rightarrow 1001$ $BA \rightarrow 1010$ $BB \rightarrow 1011$

$BC \rightarrow 1100$ $CA \rightarrow 1101$ $CB \rightarrow 1110$ $CC \rightarrow 1111$

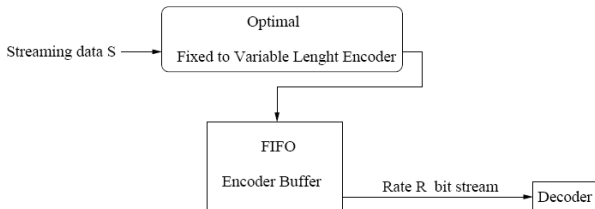


Achievability: Variable length code + FIFO queue

- Streaming data to streaming blocks $x_1, x_2, \dots \rightarrow x_1^N, x_{N+1}^{2N}, \dots$
 $1 \ll N \ll \Delta < \text{buffer}$

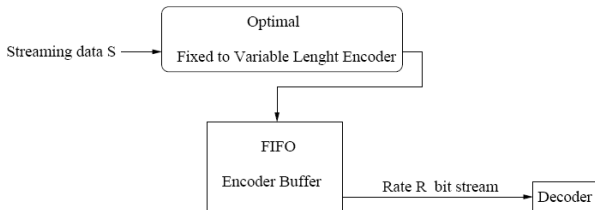
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- For each block: Tilted entropy code (Jelinek 68) or MDL (Rissanen 78)



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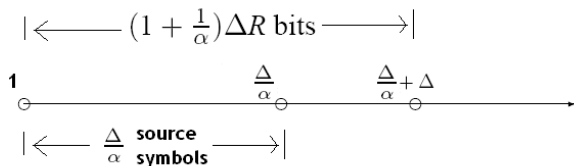
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- Decoding error \rightarrow long queueing delay
- Long queueing delay \Leftrightarrow buffer overflow (Jelinek 1968, Merhav 1991)
- Optimal among all coding schemes

Converse: a focusing bound argument

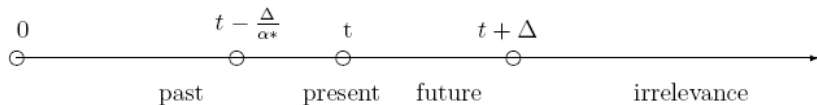
- Use $(1 + \frac{1}{\alpha})\Delta R$ bits to describe $x_1, x_2, \dots, x_{\frac{\Delta}{\alpha}}$, $\frac{\Delta}{\alpha}$ source symbols
- $\alpha = \frac{\text{future}}{\text{past}}$
 - ▶ Streaming coding with delay \rightarrow block coding
 - ▶ Block length $\frac{\Delta}{\alpha}$, rate $(1 + \alpha)R$



- Delay constrained coding \rightarrow classical fixed length block coding
 - ▶ Block error $\sim 2^{-\frac{\Delta}{\alpha}E_b((1+\alpha)R)}$
 - ▶ True for all $\alpha > 0$: $E(R) = \inf_{\alpha > 0} \frac{1}{\alpha}E_b((\alpha + 1)R)$

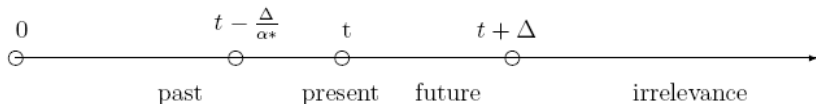
Dominant error event

- Past, present, future and remote future for decoding x_t at time $t + \Delta$



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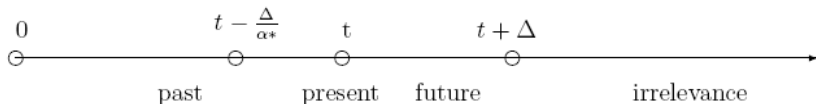


- Source behaves like the ρ^* -tilted distribution of $p_x^{\rho^*}$ from time $t - \frac{t}{\alpha^*}$ to time t

$$p_x^{\rho^*}(x) = \frac{p_x(x)^{\frac{1}{1+\rho^*}}}{\sum_{s \in \mathcal{X}} p_x(s)^{\frac{1}{1+\rho^*}}}, \quad \rho^* R = (1 + \rho^*) \log \left[\sum_x p_x(x)^{\frac{1}{1+\rho^*}} \right], \quad \alpha^* + 1 = \frac{H(p_x^{\rho^*})}{R}$$

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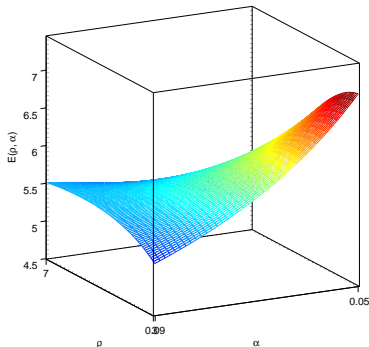
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- Parametrization $E(R) = \rho^* R$

A game theoretic perspective on $E(R)$

- (ρ^*, α^*) is the saddle point

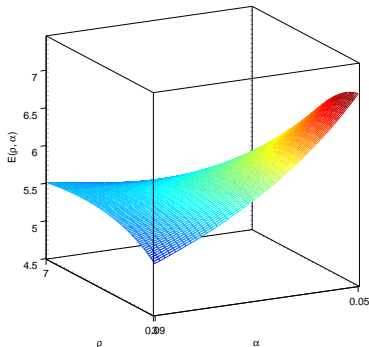
$$E(R) = \inf_{\alpha > 0} \frac{1}{\alpha} E_b((\alpha + 1)R) = \inf_{T > \alpha > 0} \sup_{\rho > 0} \frac{1}{\alpha} (\rho(1 + \alpha)R - (1 + \rho) \log[\sum_x p_x(x)^{\frac{1}{1+\rho}}])$$



A game theoretic perspective on $E(R)$

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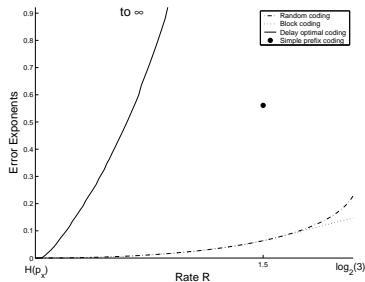
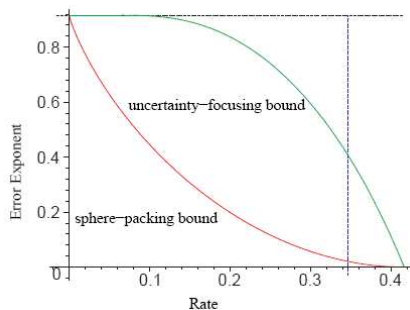
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- Payoff is the symbol error, adversary picks α , Jelinek picks ρ -tilted entropy code

Focusing operators

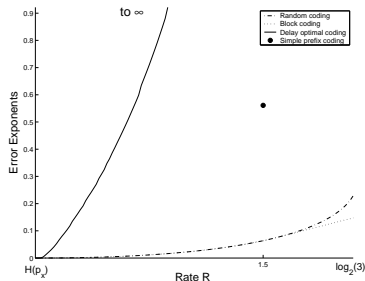
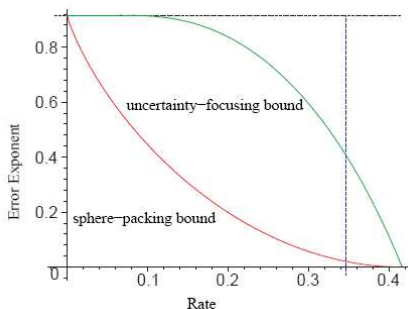
- Channel coding with feedback $\inf_{0 \leq \lambda \leq 1} \frac{E_{sp}(\lambda R)}{1-\lambda}$: (Simsek and Sahai, 2006)
- Source coding: $E(R) = \inf_{\alpha > 0} \frac{1}{\alpha} E_b((\alpha + 1)R)$



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- Duality: $\frac{\Delta}{\alpha}$ symbols using $R(\Delta + \frac{\Delta}{\alpha})$ bits \leftrightarrow $\frac{\lambda}{1-\lambda} \Delta R$ bits using $\frac{\Delta}{1-\lambda}$ channel uses



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- Distributed source coding
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3 Conclusions and future works

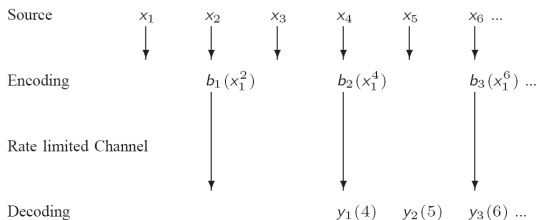
- Past vs future
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From lossless to lossy

- Temperature measurements $100.01 \simeq 100.02$, $d(x, y) \geq 0$

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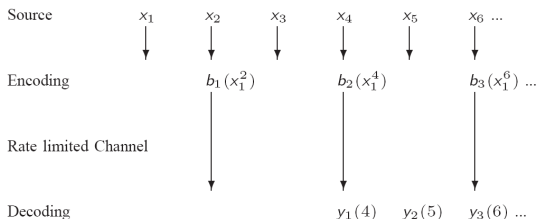


- ▶ Symbol-wise decoding error exponential decays with delay

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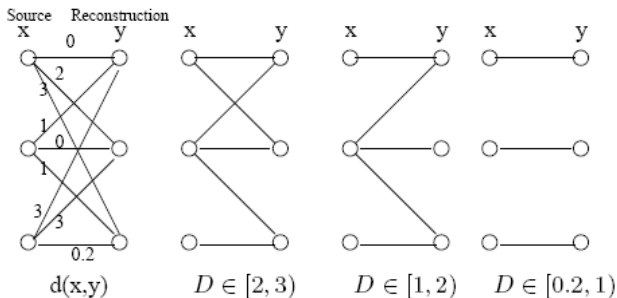
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- No-delay (Gilbert, Neuhoff 1982), average distortion (Tse 1993)

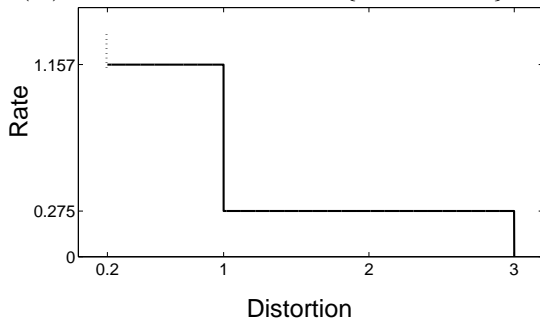
Peak Distortion Measures

- $d(x_1^n, y_1^n) = \max_i d(x_i, y_i)$
- Block coding under peak distortion \longleftrightarrow streaming lossy
- Distance $d(x, y)$ and valid reconstructions



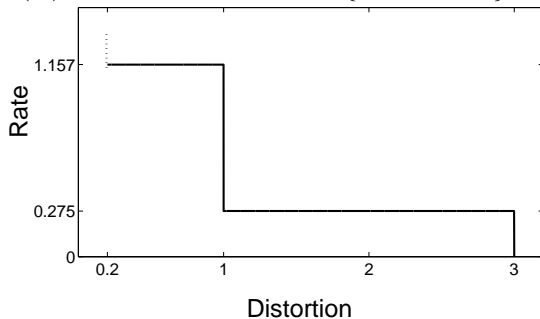
$R(D)$ is a stair function (Csiszár and Körner)

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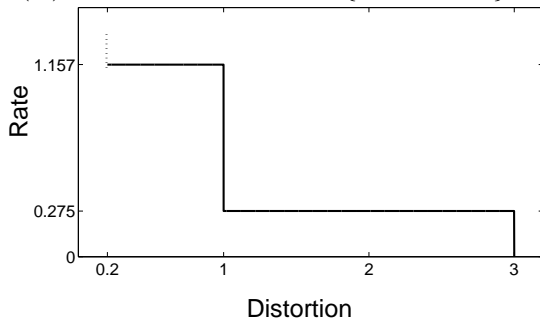
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- Block coding error exponent $E_D^b(R)$ (Marton, 1974)

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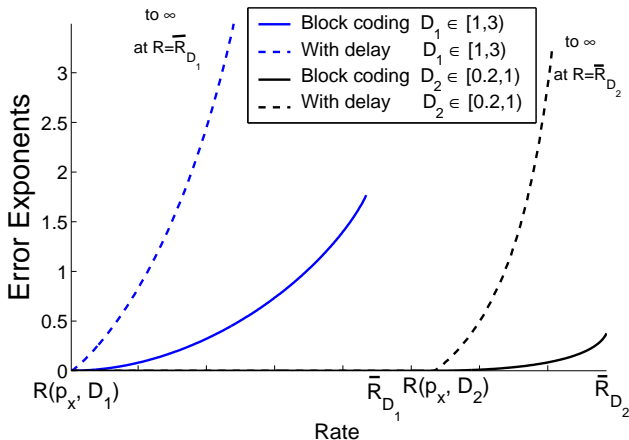
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- Block coding error exponent $E_D^b(R)$ (Marton, 1974)
- Scalar quantization is suboptimal (not lossless),
 $R(p_x, D \in [1, 3]) < H(0.9, 0.1) = 0.469$

Lossy source coding error exponent

- $\Pr(d(x_i, y_i(i + \Delta)) > D) \sim 2^{-\Delta E_D(R)}$
 - $E_D(R) = \inf_{\alpha > 0} \frac{1}{\alpha} E_D^b((\alpha + 1)R)$
 - Cannot be parameterized unlike lossless— general proof



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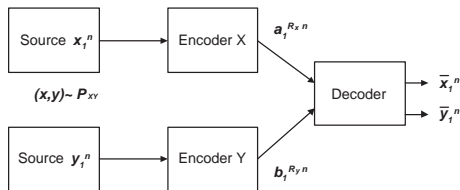
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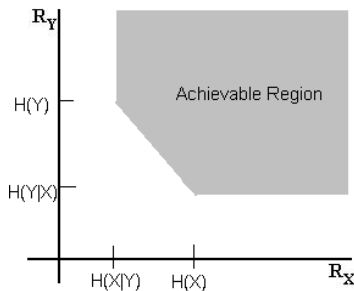
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Distributed source coding (C, Draper, Sahai 2006)

- Lossless Source Coding of Correlated Sources

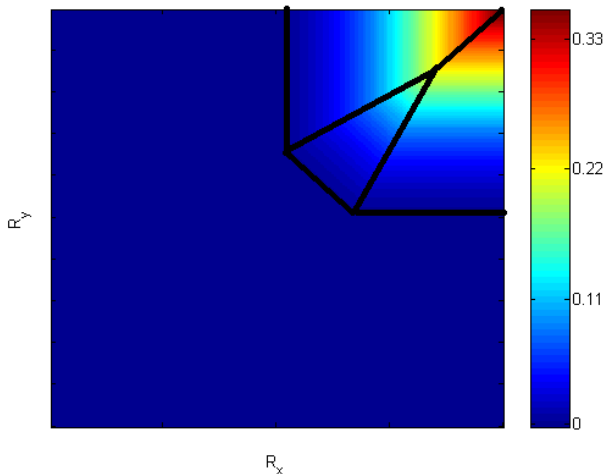


- Rate region (Slepian, Wolf)



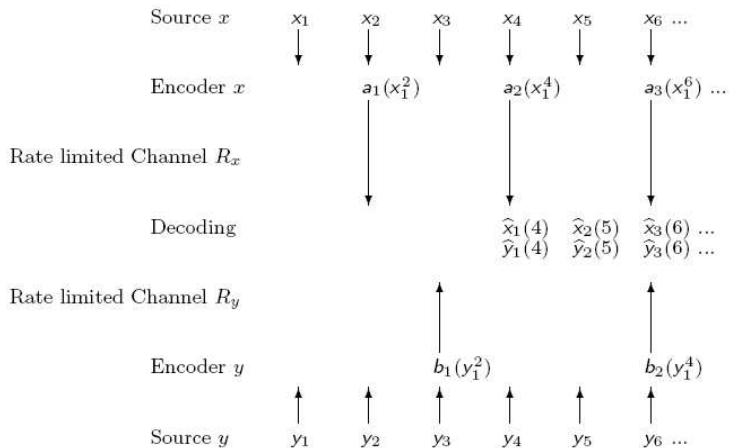
Block coding error exponents: (Gallager, Csiszár)

- $\Pr[(x^n, y^n) \neq (\hat{x}^n, \hat{y}^n)] \sim 2^{-n \min\{E_{xy}, E_{x|y}, E_{y|x}\}}$
- Three dominant error events: xy , $y|x$ and $x|y$



Streaming Slepian-Wolf coding with fixed delay

$$(x, y) \sim P_{xy}, \Delta = 3, R_x = 1/2, R_y = 1/3$$

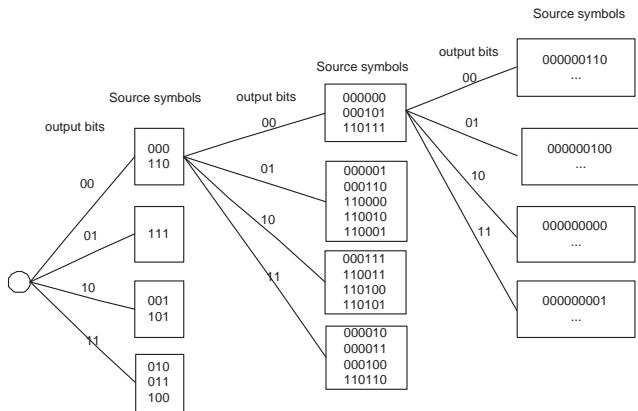


Sequential Random Binning

- Block random binning $\Pr(b(x_1^n) = b(\tilde{x}_1^n)) = 2^{-nR}$ if $x_1^n \neq \tilde{x}_1^n$

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- Sequential Random binning $\Pr(b(x_1^n) = b(\tilde{x}_1^n)) = 2^{-(n-i)R}$, t is the first position $x_i \neq \tilde{x}_i$



ML decoding (re-estimate (x_1^n, y_1^n) at time n)

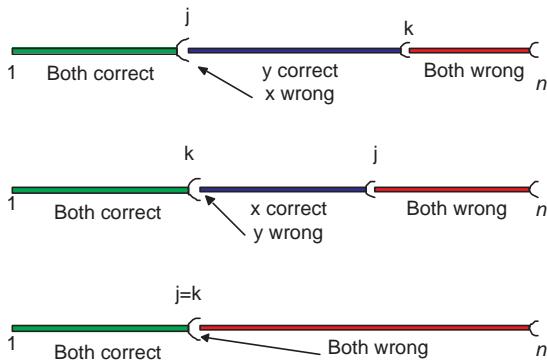
- $(\hat{x}_1^n, \hat{y}_1^n) = \arg \max_{b_X(s_1^n)=b_X(x_1^n), b_Y(t_1^n)=b_Y(y_1^n)} p_{xy}(s_1^n, t_1^n)$
 - ▶ Stack algorithm (Palaiyanur, Sahai)

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- Universal decoding rule is complicated (fighting the polynomials)
 - ▶ Sequential minimum empirical entropy (Draper, C, Sahai)

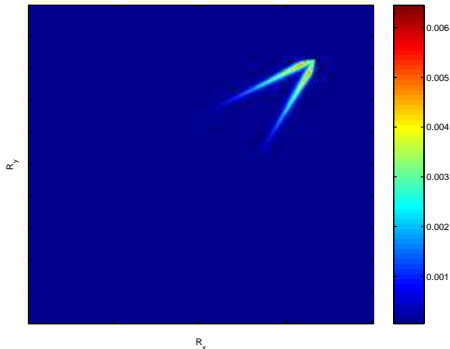
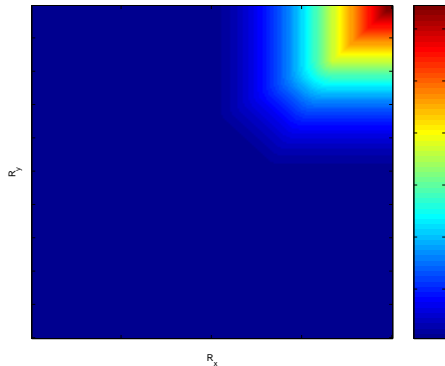
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- Partition of error events at time n (first divergent position):



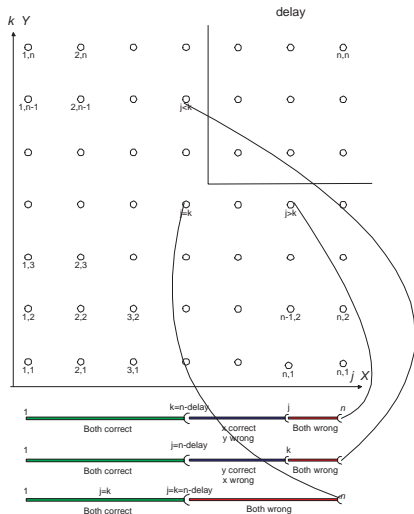
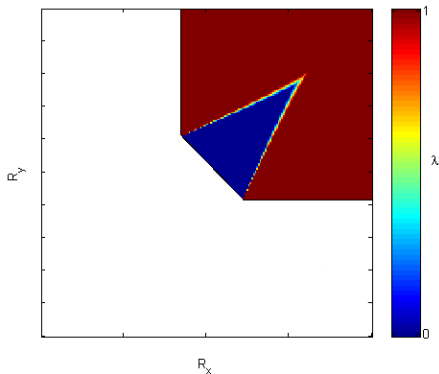
Delay constrained error exponents: $E(R_x, R_y)$ and $E_{block} - E_{delay}$

0.1	0.05
0.05	0.8



Dominant error event for streaming coding

- $$E(R_x, R_y) = \min\{\inf_{\gamma \in [0,1]} E_x(R_x, R_y, \gamma), \inf_{\gamma \in [0,1]} E_y(R_x, R_y, \gamma)\}$$



No upper bound?

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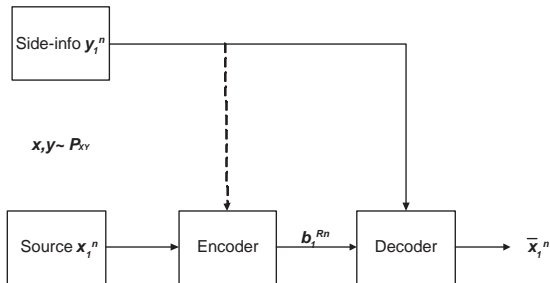
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3 Conclusions and future works

- Past vs future
- Open problems

Lossless Source Coding with side-information

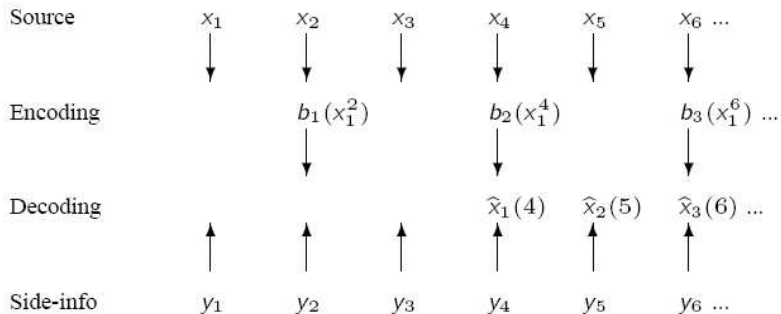
- Special case of Slepian-Wolf (Encoder Y perfect)



- ▶ $R \geq H(X|Y)$ to achieve ϵ -error probability ($x_1^n \neq \bar{x}_1^n$) - Slepian and Wolf
- ▶ Encoder side-information redundant

Streaming coding with delay

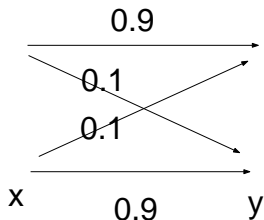
- Streaming source coding with delay constraints



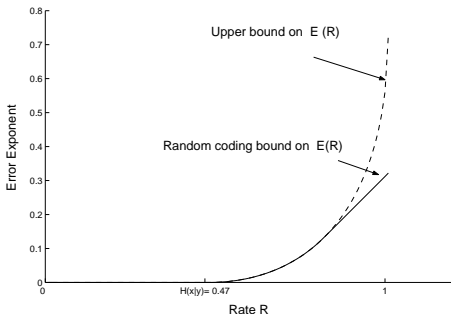
- ▶ Symbol decoding error exponential decays with delay

$$\Pr(x_i \neq \hat{x}_i(i + \Delta)) \sim 2^{-\Delta E(R)}$$

Example: x uniform and $P_{y|x}$ symmetric channel

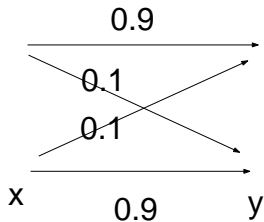


- $X \sim \text{Bernoulli}(0.5)$,
- $A \sim \text{Bernoulli}(0.1)$
- $Y = X \oplus A$

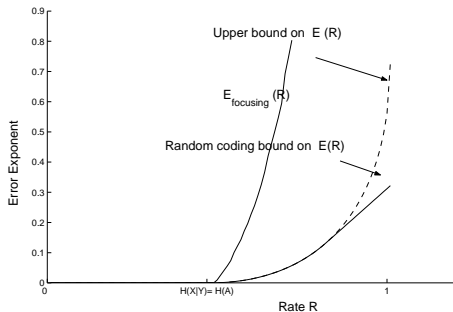


- Decoder side-info only: tight in low rate regime!

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- With encoder side-info, focusing bound.
- Price of ignorance.

Compression of Encrypted Data (Johnson et al)

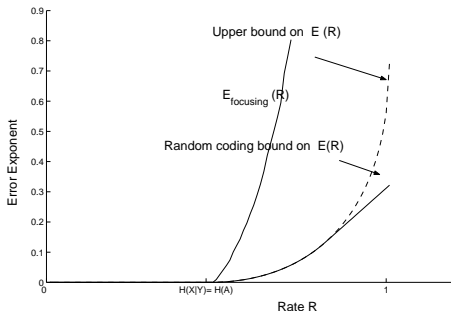
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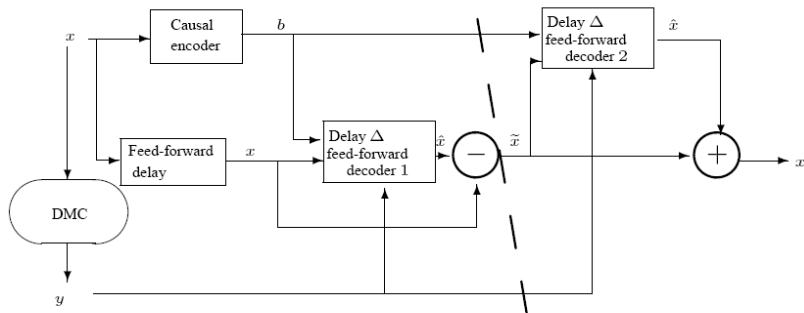
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Proof of the upper bound

- Feed-forward channel decoding (Pinsker, Sahai)
 - ▶ Joint source-channel coding

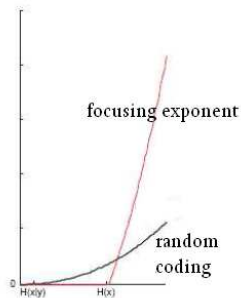
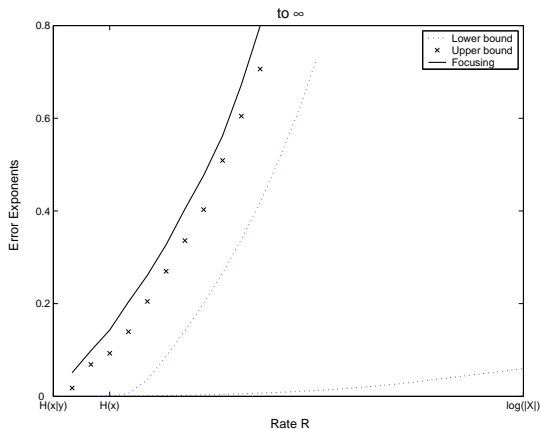


- Computational complexity/ rate tradeoff for iterative decoding (Grover, Sahai)
 - ▶ Delay \longleftrightarrow neighbors on the graph (resource)

Bounds on $E(R)$

- Lower bounds:

- ▶ Sequential random binning — $R > H(X|Y)$
- ▶ Variable length coding + FIFO — $R > H(X)$



Outline

1 Problem setup and motivation

- Motivation
- Streaming coding with delay

2 Main results

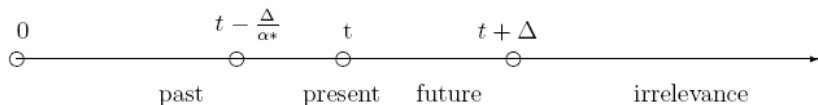
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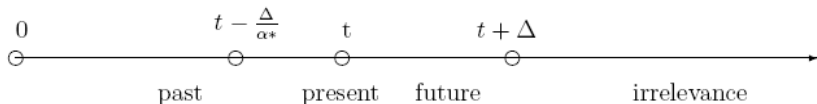
Dominant error events for optimal coding

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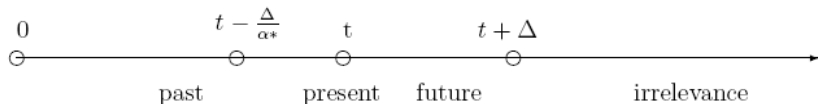
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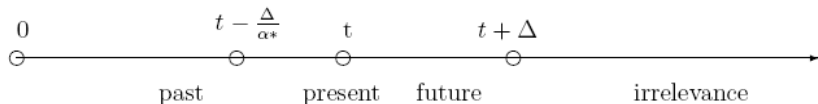
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Dominant error events for optimal coding

- Streaming source coding, channel coding with delay



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Interaction between encoder and decoder

- Focusing operator
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- From the encoder's perspective:
 - ▶ Variable length code/ Queue \rightarrow observable randomness (source)
 - ▶ Sequential random binning \rightarrow non-observable randomness (channel, decoder side-information)
 - ▶ Variable length sequential random binning? (Joint source-channel, decoder side information)

Other future directions

- Binary representation of streaming coding with delay problems (p-to-p)

	Random arrival	Non-uniform source	Noisy DMC channel	Feedback	Side-information	Distortion
lossless	0	1	0	0	0	0
lossy	0	0	0	0	0	1
decoder side-info	0	0	0	0	1	0
ongoing work	1	1	0	0	0	0
Joint SC	0	1	1	0	0	0
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- With memory?
- Universal lower bound on the error exponents— non asymptotic result.
- Convexity \cup of the focusing bound $E(R)$?